

A stability criterion for two-fluid interfaces

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Outline

General Introduction

- The One Fluid Case (Water Waves)

- The Two Fluids Case

The stability theorem

- Rigorous derivation of the equations

- Quasilinearization of the equations

- Main result and stability criterion

Handling the shallow water limit

- Nondimensionalization

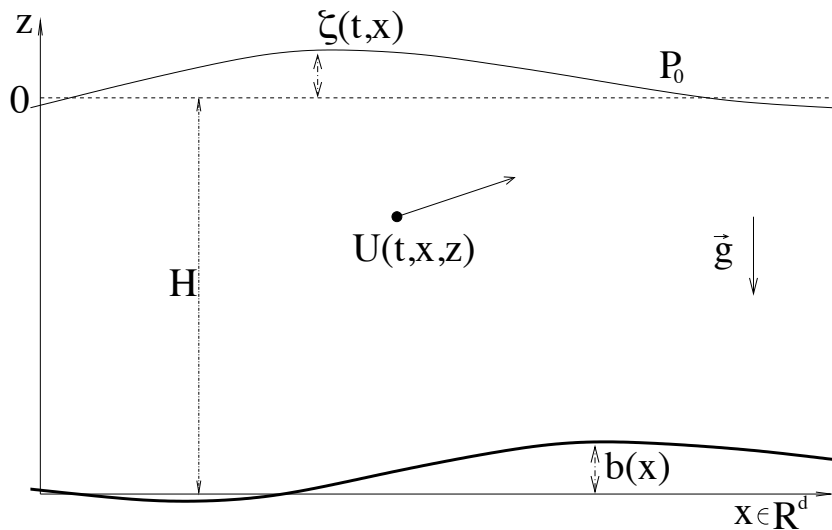
- Complications

- Practical criterion and applications

I- General Introduction

1) The one fluid case (Water Waves)

a) Notations



b) Free surface Euler equations

Equations inside the fluid domain

▶ *Incompressibility*: $\text{div}_{X,z} U = 0$

▶ *Irrotationality*: $\text{curl}_{X,z} U = 0$

▶ *Conservation of momentum (Euler equation)*:

$$\rho(\partial_t U + (U \cdot \nabla_{X,z})U) = -\nabla_{X,z} P + \rho \mathbf{g}$$

Equations at the surface

▶ Continuity of the stress tensor: $P - P_{atm} = \sigma \kappa(\zeta)$ ($\sigma \geq 0$)

▶ Bounding surface: $\partial_t \zeta - \sqrt{1 + |\nabla \zeta|^2} U_n = 0$

Equations at the rigid bottom

▶ Impermeability: $U_n = 0$

c) Free surface Bernoulli equations

Equations inside the fluid domain

▶ *Irrotationality*: $U = \nabla_{X,z} \Phi$

▶ *Incompressibility*: $\Delta_{X,z} \Phi = 0$

▶ *Bernoulli equation*:

$$\rho \left(\partial_t \Phi + \frac{1}{2} |\nabla_{X,z} \Phi|^2 \right) = -(P - P_{atm}) - \rho g z$$

Equations at the surface

▶ Continuity of the stress tensor: $P - P_{atm} = \sigma k(\zeta)$ ($\sigma \geq 0$)

▶ Bounding surface: $\partial_t \zeta - \sqrt{1 + |\nabla \zeta|^2} \partial_n \Phi = 0$

Equations at the rigid bottom

▶ Impermeability: $\partial_n \Phi = 0$

d) The Zakharov-Craig-Sulem formulation

Idea

Write the equations in terms of ζ and $\psi(t, x) = \Phi(t, X, \zeta(t, X))$

- ▶ $\partial_t \Phi|_{z=\zeta} = \partial_t \psi - (\partial_t \zeta) \partial_z \Phi|_{z=\zeta}$
- ▶ $\nabla \Phi|_{z=\zeta} = \nabla \psi - (\nabla \zeta) \partial_z \Phi|_{z=\zeta} =: \underline{V}$
- ▶ $\partial_z \Phi|_{z=\zeta} = \frac{G[\zeta] \psi + \nabla \zeta \cdot \nabla \psi}{1 + |\nabla \zeta|^2} =: \underline{W}$

where

$$G[\zeta] \psi := \sqrt{1 + |\nabla \zeta|^2} \partial_n \Phi|_{z=\zeta}$$

The operator $G[\zeta]$ is called **Dirichlet-Neumann operator**

Since $P|_{z=\zeta} = P_{atm} + \sigma\kappa(\zeta)$, the pressure disappears when we take the **trace at the surface** of the Bernoulli equation

$$\rho(\partial_t\Phi + \frac{1}{2}|\nabla_{X,z}\Phi|^2) = -(P - P_{atm}) - \rho gz.$$

After some computations, we obtain therefore

$$(1) \begin{cases} \partial_t\zeta - G[\zeta]\psi = 0, \\ \partial_t\psi + g\zeta + \frac{1}{2}|\nabla\psi|^2 - \frac{(G[\zeta]\psi + \nabla\zeta \cdot \nabla\psi)^2}{2(1 + |\nabla\zeta|^2)^2} = -\frac{\sigma}{\rho}\kappa(\zeta), \end{cases}$$

where we recall that

- ▶ $G[\zeta]\psi = \sqrt{1 + |\nabla\zeta|^2}\partial_n\Phi|_{z=\zeta}$
- ▶ $\kappa(\zeta) = -\nabla \cdot \left(\frac{\nabla\zeta}{\sqrt{1 + |\nabla\zeta|^2}}\right)$

e) Basic comments on the equations

Proposition

If $\zeta = 0$ then $G[0]\psi = |D| \tanh(H|D|)$.

Notation: $\widehat{f(D)u} = f(\xi)\widehat{u}(\xi)$.

The linearization of (1) around the rest state ($\zeta = 0, \psi = 0$) gives

$$\begin{cases} \partial_t \zeta - |D| \tanh(H|D|)\psi = 0, \\ \partial_t \psi + g\zeta = 0 \end{cases}$$

and therefore

$$(2) \quad \partial_t^2 \zeta + g|D| \tanh(H|D|)\zeta = 0.$$

Let us investigate the behavior of the linearized equations (2),

$$\partial_t^2 \zeta + g|D| \tanh(H|D|)\zeta = 0.$$

The deep water limit $H = \infty$

Since $\lim_{x \rightarrow +\infty} \tanh(x) = 1$, we replace $\tanh(H|D|)$ by 1 in (2),

$$\partial_t^2 \zeta + g|D|\zeta = 0.$$

This is a **dispersive** equation.

The shallow water limit $H \ll 1$

Since $\tanh(x) \sim_{x \rightarrow 0} x$, we replace $\tanh(H|D|)$ by $H|D|$ in (2),

$$\partial_t^2 \zeta - gH\Delta\zeta = 0.$$

This is a **non dispersive** equation (in physical terminology !!!).

- ▶ *The deep water limit coincides with the symbolic analysis*
- ▶ *The SW limit is not compatible with symbolic analysis*

f) One more formulation

Let us denote by \underline{U} the velocity at the surface,

$$\underline{U} = (\underline{V}, \underline{w}) = U|_{z=\zeta}.$$

We take the trace of the Euler equation at the surface

$$\rho(\partial_t \underline{U} + (\underline{U} \cdot \nabla_{X,z}) \underline{U})|_{z=\zeta} = -\nabla_{X,z} P|_{z=\zeta} + \rho \mathbf{g}$$

- ▶ $\partial_t U|_{z=\zeta} = \partial_t \underline{U} - (\partial_t \zeta) \partial_z U|_{z=\zeta}$
- ▶ $(\underline{U} \cdot \nabla_{X,z}) U|_{z=\zeta} = (\underline{V} \cdot \nabla) \underline{U} - (\underline{V} \cdot \nabla \zeta) \partial_z U|_{z=\zeta} + \underline{w} \partial_z U|_{z=\zeta}$
- ▶ $-\nabla_{X,z} P|_{z=\zeta} + \rho \mathbf{g} = \begin{pmatrix} -\nabla(P - P_{atm}) + \nabla \zeta \partial_z P|_{z=\zeta} \\ -\rho \mathbf{g} - \partial_z P|_{z=\zeta} \end{pmatrix}$

We get therefore (take $\sigma = 0$ here)

$$\rho(\partial_t \underline{U} + (\underline{V} \cdot \nabla) \underline{U}) = \begin{pmatrix} \nabla \zeta \partial_z P|_{z=\zeta} \\ -\rho g - \partial_z P|_{z=\zeta} \end{pmatrix},$$

which, together with the kinematic boundary condition, yields

$$(3) \quad \begin{cases} \partial_t \zeta + \underline{V} \cdot \nabla \zeta - \underline{w} = 0, \\ \partial_t \underline{V} + (\underline{V} \cdot \nabla) \underline{V} + \underline{a} \nabla \zeta = 0, \end{cases}$$

with

$$\underline{a} = -\frac{1}{\rho} \partial_z P|_{z=\zeta} = g + (\partial_t + \underline{V} \cdot \nabla) \underline{w}.$$

$$\begin{cases} \partial_t \zeta + \underline{V} \cdot \nabla \zeta - \underline{w} = 0, \\ \partial_t \underline{V} + (\underline{V} \cdot \nabla) \underline{V} + \alpha \nabla \zeta = 0, \end{cases}$$

One must of course express \underline{w} and α in terms of ζ and \underline{V} .
For the moment, let us proceed formally:

- ▶ When $\zeta = 0$ then

$$\begin{aligned} \underline{w} &= \partial_z \Phi|_{z=0} = \partial_n \Phi|_{z=0} \\ &= G[0] \psi = |D| \tanh(H|D|) \psi \\ &= -\tanh(H|D|) \frac{\nabla}{|D|} \cdot \nabla \psi \\ &= -\tanh(H|D|) \frac{\nabla}{|D|} \cdot \underline{V}. \end{aligned}$$

- ▶ When $\zeta \neq 0$ it remains true when $d = 1$ (and “almost” true when $d = 2$) that

$$\underline{w} = -\frac{\nabla}{|D|} \cdot \underline{V} + \text{lower order terms.}$$

$$(3) \quad \begin{cases} \partial_t \zeta + \underline{V} \cdot \nabla \zeta - \underline{w} = 0, \\ \partial_t \underline{V} + (\underline{V} \cdot \nabla) \underline{V} + \alpha \nabla \zeta = 0, \end{cases}$$

From the previous analysis, the principal symbol of (3) should look like

$$\begin{pmatrix} \underline{V} \cdot i\xi & i \frac{\xi^T}{|\xi|} \\ \alpha i \xi & \underline{V} \cdot i\xi \end{pmatrix}.$$

↪ Imaginary eigenvalue of multiplicity two, with a Jordan block

The system is non strictly hyperbolic

↪ Well-posedness requires therefore a **Levy condition** on the subprincipal symbol

$$\text{(Rayleigh-Taylor)} \quad \alpha = -\frac{1}{\rho} \partial_z P|_{z=\zeta} \geq \alpha_0 > 0$$

g) Nonlinear well-posedness

Theorem

Let $(\zeta^0, \nabla\psi^0)$ be regular enough and

$$\boxed{-H + \zeta^0 \geq h_{min} > 0} \quad \text{and} \quad \boxed{\alpha = -\frac{1}{\rho} \partial_z P|_{z=\zeta} \geq a_0 > 0.}$$

Then there exists a unique solution to (1) with initial condition (ζ^0, ψ^0) on a time interval $[0, T]$ for some $T > 0$.

Remark:

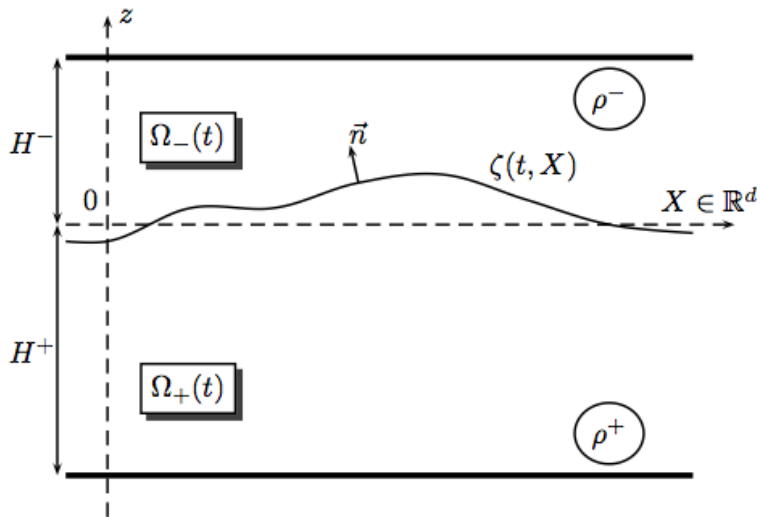
- ▶ The Rayleigh-Taylor may be automatically satisfied (infinite depth, flat bottom, ...)
- ▶ Theorem true if $\sigma > 0$ with existence time $T_\sigma \rightarrow T$ as $\sigma \rightarrow 0$.

References (Local existence): Wu, Lindblad, L., Ambrose-Masmoudi, Coutand-Shkoller, Shatah-Zeng, Iguchi, Cordoba²-Gancedo, Ming-Zhang, Rousset-Tzvetkov, Alazard-Burq-Zuily, etc.

I- General Introduction

2) The two fluids case

a) Notations



b) Free interface Euler equations

Equations in Fluid +

- ▶ $\operatorname{div}_{X,z} U^+ = 0$
- ▶ $\operatorname{curl}_{X,z} U^+ = 0$
- ▶ $\rho^+ (\partial_t U^+ + (U^+ \cdot \nabla_{X,z}) U^+) = -\nabla_{X,z} P^+ + \rho^+ \mathbf{g}$.

Equations in Fluid -

- ▶ $\operatorname{div}_{X,z} U^- = 0$
- ▶ $\operatorname{curl}_{X,z} U^- = 0$
- ▶ $\rho^- (\partial_t U^- + (U^- \cdot \nabla_{X,z}) U^-) = -\nabla_{X,z} P^- + \rho^- \mathbf{g}$.

Equations at the interface

- ▶ $\boxed{[[P^\pm]] = \sigma \kappa(\zeta)}$ with the notation $[[A^\pm]] = A^+ - A^-$.
- ▶ $\partial_t \zeta - \sqrt{1 + |\nabla \zeta|^2} U_n^\pm = 0 \rightsquigarrow \boxed{U_n^+ = U_n^-}$

Equations at the rigid boundaries

- ▶ $U_n^+ = 0$ at $z = -H^+$
- ▶ $U_n^- = 0$ at $z = H^-$

c) Free interface Bernoulli equations

Equations in Fluid +

- ▶ $U^+ = \nabla_{X,z}\Phi^+$
- ▶ $\Delta_{X,z}\Phi^+ = 0$
- ▶ $\rho^+(\partial_t\Phi^+ + \frac{1}{2}|\nabla_{X,z}\Phi^+|^2) = -(P^+ - P_{atm}) - \rho^+gz.$

Equations in Fluid -

- ▶ $U^- = \nabla_{X,z}\Phi^-$
- ▶ $\Delta_{X,z}\Phi^- = 0$
- ▶ $\rho^-(\partial_t\Phi^- + \frac{1}{2}|\nabla_{X,z}\Phi^-|^2) = -(P^- - P_{atm}) - \rho^-gz.$

Equations at the interface

- ▶ $[[P^\pm]] = \sigma\kappa(\zeta)$
- ▶ $\partial_t\zeta - \sqrt{1 + |\nabla\zeta|^2}\partial_n\Phi^\pm = 0$

Equations at the rigid boundaries

- ▶ $\partial_n\Phi^+ = 0$ at $z = -H^+$
- ▶ $\partial_n\Phi^- = 0$ at $z = H^-$

d) Reduction at the interface

Idea

Eliminate the pressure from the Bernoulli equations

$$\rho^+ \left(\partial_t \Phi^+ + \frac{1}{2} |\nabla_{X,z} \Phi^+|^2 \right) = -(P^+ - P_{atm}) - \rho^+ g z$$

$$\rho^- \left(\partial_t \Phi^- + \frac{1}{2} |\nabla_{X,z} \Phi^-|^2 \right) = -(P^- - P_{atm}) - \rho^- g z$$

using the relation $\llbracket P^\pm \rrbracket = \sigma \kappa(\zeta)$.

$$\rightsquigarrow \psi = \underline{\rho}^+ \psi^+ - \underline{\rho}^- \psi^-$$

where $\psi^\pm(t, X) = \Phi^\pm(t, X, \zeta(t, X))$ and $\underline{\rho}^\pm = \frac{\rho^\pm}{\rho^+ + \rho^-}$.

Define **Dirichlet-Neumann operators** for the upper and lower fluids,

$$G^\pm \psi^\pm = G^\pm[\zeta] \psi^\pm := \sqrt{1 + |\nabla \zeta|^2} \partial_n \Phi^\pm \Big|_{z=\zeta}$$

where

$$\begin{cases} \Delta_{X,z} \Phi^\pm = 0 & \text{in } \Omega^\pm, \\ \Phi^\pm \Big|_{z=\zeta} = \psi^\pm, & \partial_n \Phi^\pm \Big|_{z=\mp H^\pm} = 0. \end{cases}$$

CAUTION: Always UPWARD normal derivative!

With $g' = g(\underline{\rho}^+ - \underline{\rho}^-)$ the equations of motion then become

$$(4) \quad \begin{cases} \partial_t \zeta - G^\pm \psi^\pm = 0, \\ \partial_t \psi + g' \zeta + \frac{1}{2} [\underline{\rho}^\pm |\nabla \psi^\pm|^2] - \frac{1}{2} \frac{[\underline{\rho}^\pm (G^\pm \psi^\pm + \nabla \zeta \cdot \nabla \psi^\pm)]}{1 + |\nabla \zeta|^2} = -\frac{\sigma}{\rho^+ + \rho^-} \kappa(\zeta) \end{cases}$$

$$(4) \quad \begin{cases} \partial_t \zeta - G^\pm \psi^\pm = 0, \\ \partial_t \psi + g' \zeta + \frac{1}{2} [\underline{\rho}^\pm |\nabla \psi^\pm|^2] - \frac{1}{2} \frac{[\underline{\rho}^\pm (G^\pm \psi^\pm + \nabla \zeta \cdot \nabla \psi^\pm)]}{1 + |\nabla \zeta|^2} = -\frac{\sigma}{\rho^+ + \rho^-} \kappa(\zeta) \end{cases}$$

Comments:

- ▶ We recall that $G^+ \psi^+ = G^- \psi^-$.
- ▶ When $\zeta = 0$,

$$G^+[0] = |D| \tanh(H^+ |D|) \quad \text{and} \quad G^-[0] = -|D| \tanh(H^- |D|)$$

- ▶ We need to express ψ^\pm in terms of ζ and $\psi = \underline{\rho}^+ \psi^+ - \underline{\rho}^- \psi^-$.

e) Basic comments on the equations

The linearization of (4) around the rest state ($\zeta = 0, \psi^\pm = 0$) gives

$$\begin{cases} \partial_t \zeta - G^\pm[0] \psi^\pm = 0, \\ \partial_t \psi + g' \zeta = 0. \end{cases}$$

In order to express ψ^\pm in terms of ζ and ψ , we solve

$$\begin{cases} |D| \text{th}^+ \psi^+ + |D| \text{th}^- \psi^- = 0 \\ \underline{\rho}^+ \psi^+ - \underline{\rho}^- \psi^- = \psi, \end{cases}$$

where $\boxed{\text{th}^\pm = \tanh(H^\pm |D|)}$.

$$G^+[0] \psi^+ = G^-[0] \psi^- = \boxed{G[0] \psi} = |D| \frac{\text{th}^+ \text{th}^-}{\underline{\rho}^+ \text{th}^- + \underline{\rho}^- \text{th}^+} \psi.$$

For the one fluid case, the linearized equation around $(0, 0)$ was

$$(2) \quad \partial_t^2 \zeta + g|D| \tanh(H^+|D|)\zeta = 0.$$

The **two fluids** generalization is

$$(5) \quad \partial_t^2 \zeta + g'|D| \frac{\underline{\rho}^+ \text{th}^- + \underline{\rho}^- \text{th}^+}{\underline{\rho}^+ \text{th}^- + \underline{\rho}^- \text{th}^+} \zeta = 0.$$

The deep water limit $H = \infty$

$$\partial_t^2 \zeta + g'|D|\zeta = 0.$$

The shallow water limit $H^\pm \ll 1$

$$\partial_t^2 \zeta - g'H\Delta = 0,$$

where $H = \frac{H^+ H^-}{\underline{\rho}^+ H^- + \underline{\rho}^- H^+}$.

f) One more formulation

As for the water waves, write the equations in ζ and $\underline{U}^\pm = U_{|z=\zeta}^\pm$,

$$(6) \quad \begin{cases} \partial_t \zeta + \underline{V}^\pm \cdot \nabla \zeta - \underline{w}^\pm = 0, \\ \partial_t [\underline{\rho}^\pm \underline{V}^\pm] + [\underline{\rho}^\pm (\underline{V}^\pm \cdot \nabla) \underline{V}^\pm] + \mathbf{a} \nabla \zeta = -\frac{\sigma}{\rho^+ + \rho^-} \nabla \kappa(\zeta), \end{cases}$$

with

$$\mathbf{a} = -\frac{1}{\rho^+ + \rho^-} [\partial_z P_{|z=\zeta}^\pm] = \mathbf{g}' + [\underline{\rho}^\pm (\partial_t + \underline{V}^\pm \cdot \nabla) \underline{w}^\pm].$$

IMPORTANT: Write $[\underline{\rho}^\pm (\underline{V}^\pm \cdot \nabla) \underline{V}^\pm]$ in terms of ζ and $[\underline{\rho}^\pm \underline{V}^\pm]$:

$$[\underline{\rho}^\pm (\underline{V}^\pm \cdot \nabla) \underline{V}^\pm] = \underbrace{[\underline{V}^\pm] \cdot \nabla \langle \underline{\rho}^\pm \underline{V}^\pm \rangle}_{\rightsquigarrow \text{Kelvin-Helmholtz instability}} + \langle \underline{V}^\pm \rangle \cdot \nabla [\underline{\rho}^\pm \underline{V}^\pm]$$

\rightsquigarrow We need to find \underline{V}^\pm , \underline{w}^\pm in terms of ζ and $[\underline{\rho}^\pm \underline{V}^\pm]$.

Example: Linearization around $\zeta = 0$, $\underline{U}^\pm = (c^\pm, 0)$

$$(6)_1 \quad \partial_t \zeta + \underbrace{\underline{V}^\pm \cdot \nabla \zeta - \underline{w}^\pm}_{= -\sqrt{1+|\nabla \zeta|^2} U_n^\pm \sim -U_n^\pm} = 0$$

- ▶ As in the water waves case, let us write $\underline{w}^\pm \sim \mp \frac{\nabla}{|D|} \cdot \underline{V}^\pm$
- ▶ Therefore, $U_n^+ = U_n^- \sim -c^\pm \cdot \nabla \zeta \mp \frac{\nabla}{|D|} \cdot \underline{V}^\pm$
- ▶ We are therefore led to solve

$$\begin{cases} \frac{\nabla}{|D|} \cdot \underline{V}^+ + \frac{\nabla}{|D|} \cdot \underline{V}^- &= -[c^\pm] \cdot \nabla \zeta \\ \underline{\rho}^+ \underline{V}^+ - \underline{\rho}^- \underline{V}^- &= [\underline{\rho}^\pm \underline{V}^\pm]. \end{cases}$$

- ▶ We find

$$U_n^\pm \sim -(\underline{\rho}^+ c^+ + \underline{\rho}^- c^-) \cdot \nabla \zeta - \frac{\nabla}{|D|} \cdot [\underline{\rho}^\pm \underline{V}^\pm]$$

$$(6)_2 \quad \partial_t \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket + \llbracket \underline{\rho}^\pm (\underline{V}^\pm \cdot \nabla) \underline{V}^\pm \rrbracket + \mathbf{a} \nabla \zeta = - \frac{\sigma}{\rho^+ + \rho^-} \nabla \kappa(\zeta)$$

- ▶ We linearize

$$\llbracket \underline{\rho}^\pm (\underline{V}^\pm \cdot \nabla) \underline{V}^\pm \rrbracket \sim \llbracket \mathbf{c}^\pm \rrbracket \cdot \nabla \langle \underline{\rho}^\pm \underline{V}^\pm \rangle + \langle \mathbf{c}^\pm \rangle \cdot \nabla \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket$$

- ▶ Proceeding as above, we find

$$\llbracket \mathbf{c}^\pm \rrbracket \cdot \nabla \langle \underline{\rho}^\pm \underline{V}^\pm \rangle \sim \frac{1}{2} (\underline{\rho}^+ - \underline{\rho}^-) \llbracket \mathbf{c}^\pm \rrbracket \cdot \nabla \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket + \underbrace{\underline{\rho}^+ \underline{\rho}^-}_{\text{skel skel skel}} \frac{1}{2} (\llbracket \mathbf{c}^\pm \rrbracket \cdot \nabla)^2 \frac{\nabla}{|D|} \zeta$$

- ▶ We linearize $\nabla \kappa(\zeta) \sim -\Delta \nabla \zeta$

The linearized equations are therefore

$$\begin{cases} \partial_t \zeta + \tilde{c} \cdot \nabla \zeta + \frac{\nabla}{|D|} \cdot \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket = 0 \\ \partial_t \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket + \tilde{c} \cdot \nabla \llbracket \underline{\rho}^\pm \underline{V}^\pm \rrbracket + (\mathfrak{a} - \mathbf{KH} - \frac{\sigma}{\rho^+ + \rho^-} \Delta) \nabla \zeta = 0, \end{cases}$$

with

$$\tilde{c} = (\underline{\rho}^+ c^+ + \underline{\rho}^- c^-)$$

and

$$\mathbf{KH} = -\frac{1}{2} \underline{\rho}^+ \underline{\rho}^- \frac{(\llbracket c^\pm \rrbracket \cdot \nabla)^2}{|D|} \geq 0$$

↪ Hyperbolicity condition:

$$\mathfrak{a} + \frac{1}{2} \underline{\rho}^+ \underline{\rho}^- \frac{(\llbracket c^\pm \rrbracket \cdot \xi)^2}{|\xi|} + \frac{\sigma}{\rho^+ + \rho^-} |\xi|^2 \geq 0$$

↪ Kelvin stability criterion

$$g(\rho^+ - \rho^-) > \frac{(\rho^+ \rho^-)}{4\sigma(\rho^+ + \rho^-)^2} \|\llbracket c^\pm \rrbracket\|^4$$

g) Nonlinear analysis

Theorem ($\sigma = 0$)

- ▶ ($d = 1$) The two fluids Euler equations are *ill posed* in any functional space B such that

$$C^\infty \subsetneq B \subset C^{1+\alpha}.$$

- ▶ They are *well posed* for analytic data.

Proof.

1) Iguchi-Tanaka-Tani, Lebeau, Kamotski-Lebeau, Wu, etc.

Because of the ellipticity of the symbol.

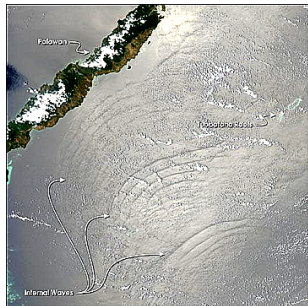
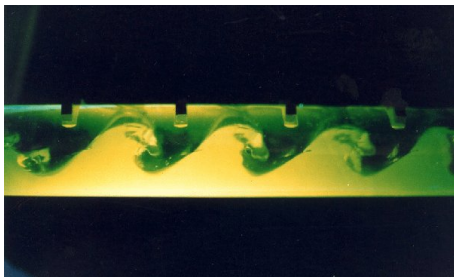
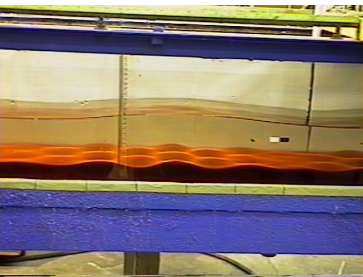
Indeed the previous analysis shows that (with $\tilde{c} = 0$),

$$\partial_t^2 \zeta + \alpha |D| \zeta + \frac{1}{2} \underline{\rho}^+ \underline{\rho}^- \|\llbracket c^\pm \rrbracket\|^2 \Delta \zeta = 0.$$

2) Duchon-Robert, Sulem², Sulem²-Bardos: Cauchy-Kowaleski □

Problem:

Interfacial wave do exist!



Theorem ($\sigma \neq 0$)

With surface tension, the equations are well-posed with Sobolev regularity over a time interval $[0, T_\sigma]$.

References: Iguchi-Tanaka-Tani, Ambrose-Masmoudi, Shatah-Zeng, Cheng-Coutand-Shkoller, Pusateri, etc.

Problem:

One has $T_\sigma \rightarrow 0$ as $\sigma \rightarrow 0$.

Question:

How to we recover the solution of the water waves equations without surface tension as $\sigma \rightarrow 0$ and $\underline{\rho}^- \rightarrow 0$?

Theorem (Pusateri)

Convergence to the solution of the water waves equations as $\sigma \rightarrow 0$ and $\underline{\rho}^- \rightarrow 0$ provided that

$$(\underline{\rho}^-)^2 \leq \sigma^{7/3}.$$

Problem:

This does not explain the observation of interfacial waves when $\underline{\rho}^- = \underline{\rho}^+ - \varepsilon$, $\varepsilon \ll 1$ (internal waves).

Question:

Such waves exist and are very well described by asymptotic models (shallow water, KdV, etc.). How can we explain their existence?

Remark: There is **no surface tension** in these asymptotic models.

Paradox:

Surface tension is necessary for the wave to exist but does not play any role on its dynamics.

Goal:

Find a criterion that

- ▶ Generalizes the Taylor criterion for two fluids interfaces
- ▶ Acts as a nonlinear version of Kelvin's criterion

Remark: The **linear** version of the Rayleigh-Taylor criterion $-\partial_z P > 0$ is $g > 0$.

$$(*) \quad \llbracket -\partial_z P_{|z=\zeta}^\pm \rrbracket > \frac{1}{4} \frac{(\rho^+ \rho^-)^2}{\sigma(\rho^+ + \rho^-)^2} c(\zeta^0) \llbracket \underline{V}^\pm \rrbracket^4$$

Theorem

Let $(\zeta^0, \nabla \psi^0)$ be regular enough and such that

$$H^\pm \mp \zeta^0 \geq h_{min} > 0 \quad \text{and } (*) \text{ is satisfied}$$

Then there is a local solution to (4) on a time interval that depends on σ through (*) only.

Remark: **Local** solutions were known to exist; the theorem furnishes **stable** (in the sense of observability) solutions.

$$(*) \quad \llbracket -\partial_z P_{|z=\zeta}^\pm \rrbracket > \frac{1}{4} \frac{(\rho^+ \rho^-)^2}{\sigma(\rho^+ + \rho^-)^2} c(\zeta^0) \llbracket \underline{V}^\pm \rrbracket^4$$

$$(RT) \quad -\partial_z P_{|z=\zeta} > 0$$

$$(K) \quad g(\rho^+ - \rho^-) > \frac{(\rho^+ \rho^-)}{4\sigma(\rho^+ + \rho^-)^2} \llbracket \underline{c}^\pm \rrbracket^4$$

Corollary

Convergence to the solution of the water waves equations as $\sigma \rightarrow 0$ and $\underline{\rho}^- \rightarrow 0$ provided that

$$(\underline{\rho}^-)^2 \ll \sigma.$$

Question:

What about internal waves? Only hope:

$$\llbracket -\partial_z P_{|z=\zeta}^\pm \rrbracket \gg 1 \quad \text{or} \quad \llbracket \underline{V}^\pm \rrbracket \ll 1$$

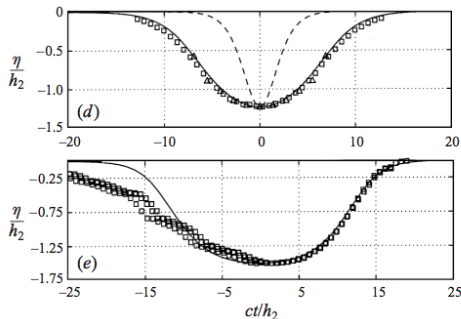
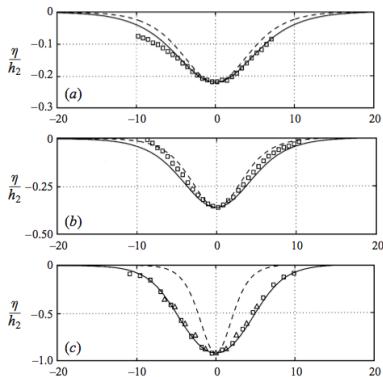
Problem:

How do we have an *a priori* knowledge of these quantities?

Goal:

We would like to be able to answer the question:

Is a wave of amplitude a and wavelength λ stable (observable)?



Grue et al. J. Fluid Mechanics, 1999.

It is possible to answer this question by asymptotic considerations.

Let

- ▶ a : typical amplitude of the wave
- ▶ λ : typical wavelength
- ▶ $H = \frac{H^+ H^-}{\underline{\rho}^+ H^- + \underline{\rho}^- H^+}$: typical depth

and

- ▶ $\mu = \frac{H^2}{\lambda^2}$: shallowness parameter
- ▶ $\Upsilon = (\underline{\rho}^+ \underline{\rho}^-)^2 \frac{a^4}{H^2} \frac{(\rho^+ + \rho^-) g'}{4\sigma}$: “stability” parameter

Theorem

The result of the previous theorem is uniformly true as $\mu \rightarrow 0$ (shallow water regime).

A *practical* stability criterion is then

$$\Upsilon \ll 1$$

II- The Stability Theorem

1) Rigorous derivation of the equations

In order to study

$$(1) \quad \begin{cases} \partial_t \zeta - G^\pm \psi^\pm = 0, \\ \partial_t \psi + g' \zeta + \frac{1}{2} [\underline{\rho}^\pm |\nabla \psi^\pm|^2] - \frac{1}{2} \frac{[\underline{\rho}^\pm (G^\pm \psi^\pm + \nabla \zeta \cdot \nabla \psi^\pm)]}{1 + |\nabla \zeta|^2} = -\frac{\sigma}{\rho^+ + \rho^-} \kappa(\zeta), \end{cases}$$

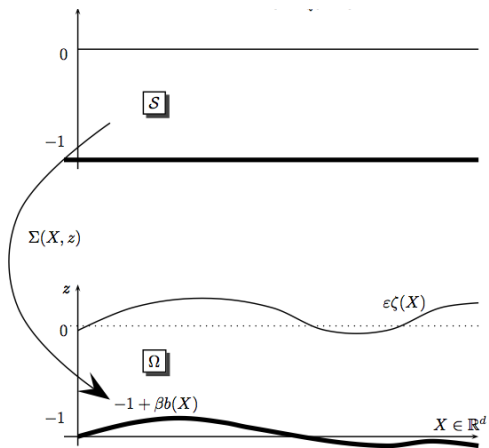
we need to express ψ^\pm in terms of ζ and $\psi = \underline{\rho}^+ \psi^+ - \underline{\rho}^- \psi^-$.

Remark: One easily checks that

$$G^\pm[\zeta, H^\pm] = \frac{1}{H^\pm} G^\pm\left[\frac{1}{H^\pm} \zeta, 1\right].$$

\rightsquigarrow In the analysis of the DN operators, we take $H^\pm = 1$.

a) Some facts on the DN operator



$$H^\pm \pm \zeta \geq h_{min}$$

We write $\phi = \Phi \circ \Sigma$; then

$$\Delta_{X,z} \Phi = 0 \text{ in } \Omega \quad \rightsquigarrow \quad \nabla_{X,z} \cdot P(\Sigma) \nabla_{X,z} \phi = 0 \text{ in } S.$$

We have the following properties:

- ▶ (P1) $G^+ \psi = \partial_n \phi|_{z=0}$ ($= \mathbf{e}_z \cdot P(\Sigma) \nabla_{X,z} \phi|_{z=0}$)
- ▶ (P2) G^+ is **positive** and **symmetric** for the L^2 -scalar product
- ▶ (P3) $\zeta \mapsto G^+[\zeta] \psi$ is analytic and

$$dG^+(h)\psi = -G^+(h\underline{w}^+) - \nabla \cdot (h\underline{V}^+)$$

Remark: Similar properties also hold for G^-

Definition (Beppo-Levy spaces)

For all $s \geq 0$, we define

$$\dot{H}^{s+1} = \{f \in L^2_{loc}(\mathbb{R}^d), \nabla f \in H^s(\mathbb{R}^d)^d\} / \mathbb{R}.$$

Let $t_0 > d/2$ and $\zeta \in H^{t_0+2}(\mathbb{R}^d)$. Then, for all $0 \leq s \leq t_0 + 1$,

- ▶ (P4) $G^+[\zeta] : \dot{H}^{s+1/2} \rightarrow H^{s-1/2}$ and

$$\boxed{|G^+ \psi|_{H^{s-1/2}} \leq M |\nabla \psi|_{H^{s-1/2}}} = M |\psi|_{\dot{H}^{s+1/2}}.$$

- ▶ (P5) For all $\psi_1, \psi_2 \in \dot{H}^{s+1/2}$,

$$\boxed{|(\Lambda^s G^+ \psi_1, \Lambda^s \psi_2)| \leq M |\nabla \psi_1|_{H^{s-1/2}} |\nabla \psi_2|_{H^{s-1/2}}}$$

- ▶ (P6) If $\psi^\pm = \phi^\pm|_{z=0}$ then

$$\boxed{|\psi^\pm|_{\dot{H}^{s+1/2}} \leq M \|\Lambda^s \nabla_{X,z} \phi^\pm\|_2}$$

Notation: $M = M(\frac{1}{h_{min}}, |\zeta|_{H^{t_0+2}})$.